Function Optimization with Local Search

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Russell and Norvig, 3rd Edition, Sections 4.1 and 4.2

These slides are new and can contain mistakes and typos. Please report them to Sven (skoenig@usc.edu).

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Gradient Descent Finding a local minimum of a differentiable function f(x₁, x₂, ..., x_n) with gradient descent (for a small positive learning rate α) Initialize x₁, x₂, ..., x_n with random values Repeat until local minimum reached For all x_i in parallel x_i := x_i - α d f(x₁, x₂, ..., x_n) / d x_i









Local Search for Function Optimization

- From now on
 - Function maximization instead of minimization (called gradient ascent or hillclimbing)
 - discrete rather than continuous functions

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Hillclimbing • Combine with random restarts function HILL-CLIMBING(problem) returns a solution state inputs: problem, a problem static current, a node next, a node current \leftarrow MAKE-NODE(INITIAL-STATE[problem]) hoop do next ← a highest-valued successor of current if VALUE[next] < VALUE[current] then return current current ← next end</pre>



















Local Search

- Want to play around with local search algorithms for constraint satisfaction?
- Go here: http://aispace.org/hill/