

# Fast and Loose in Bounded Suboptimal Heuristic Search

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# Motivation

- Finding optimal solutions is prohibitively expensive.

Introduction

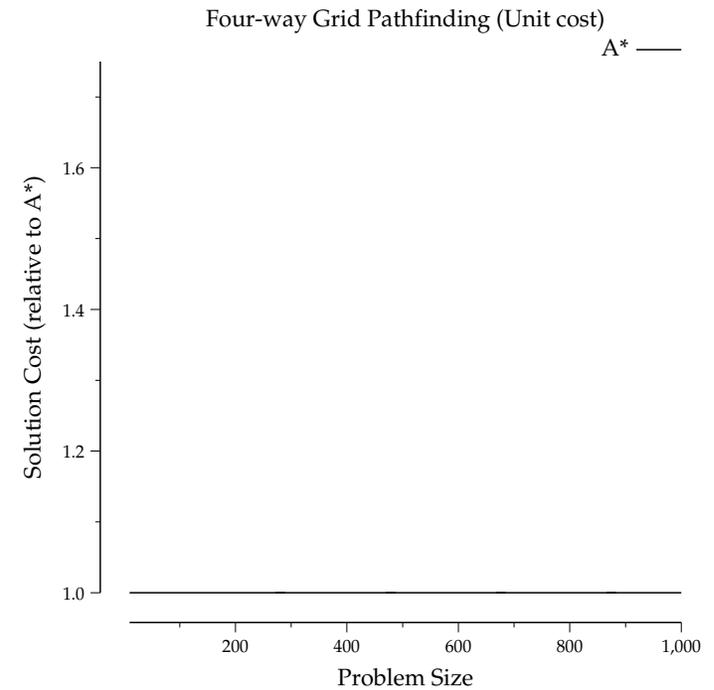
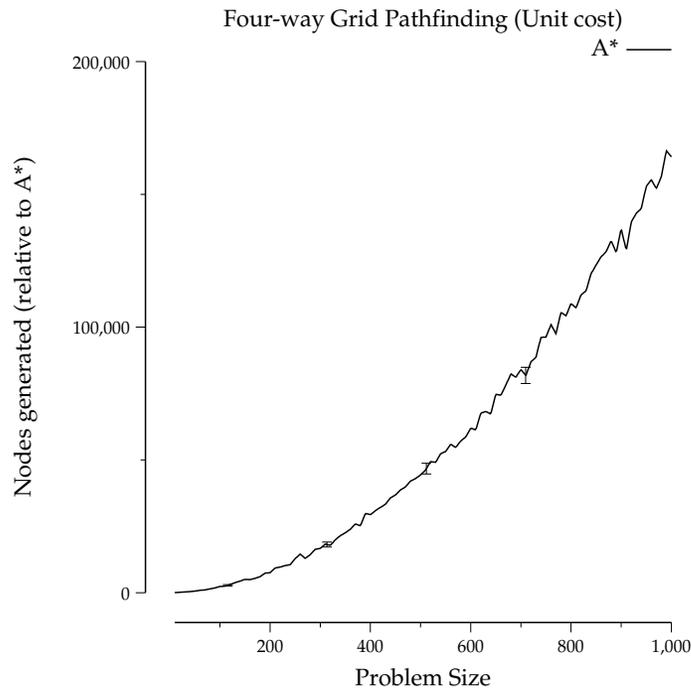
■ Motivation

Weighted  $A^*$

Clamped Adaptive

Optimistic Search

Conclusion



# Motivation

Introduction

■ Motivation

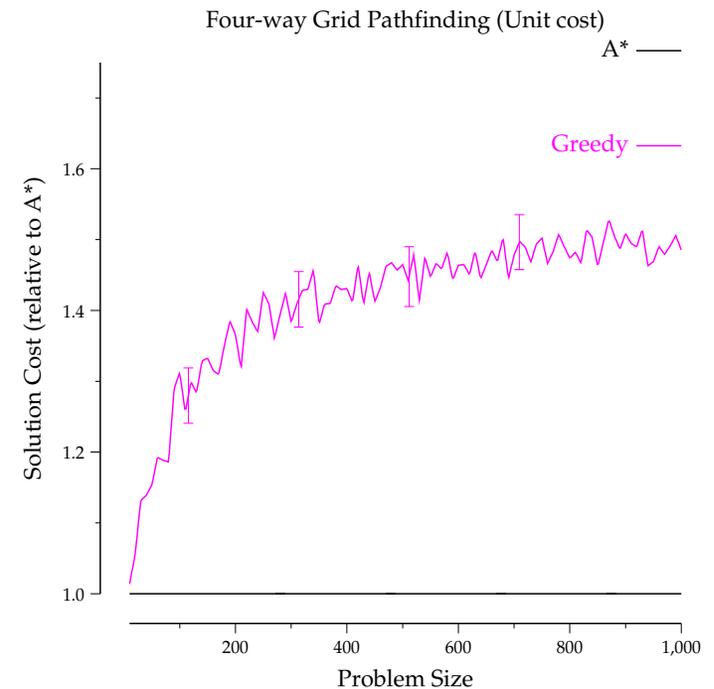
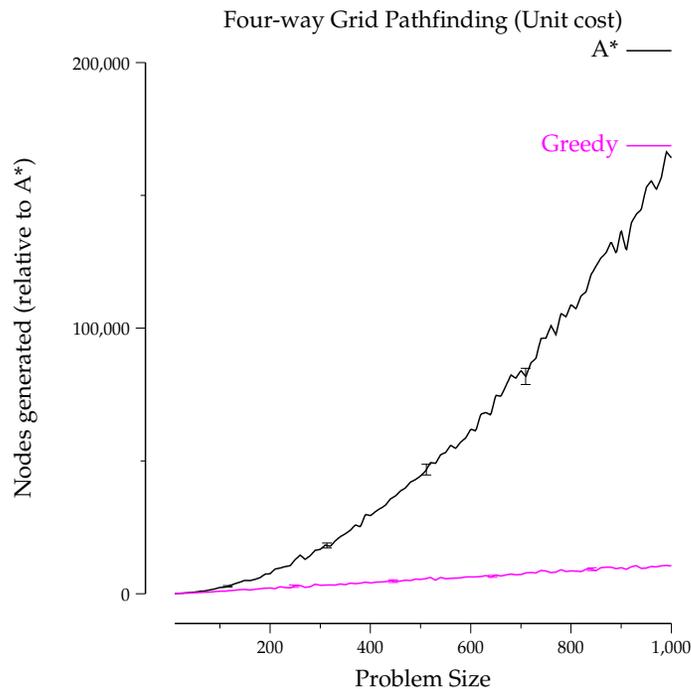
Weighted  $A^*$

Clamped Adaptive

Optimistic Search

Conclusion

- Finding optimal solutions is prohibitively expensive.
- Its nice to limit suboptimality.



# Motivation

Introduction

■ Motivation

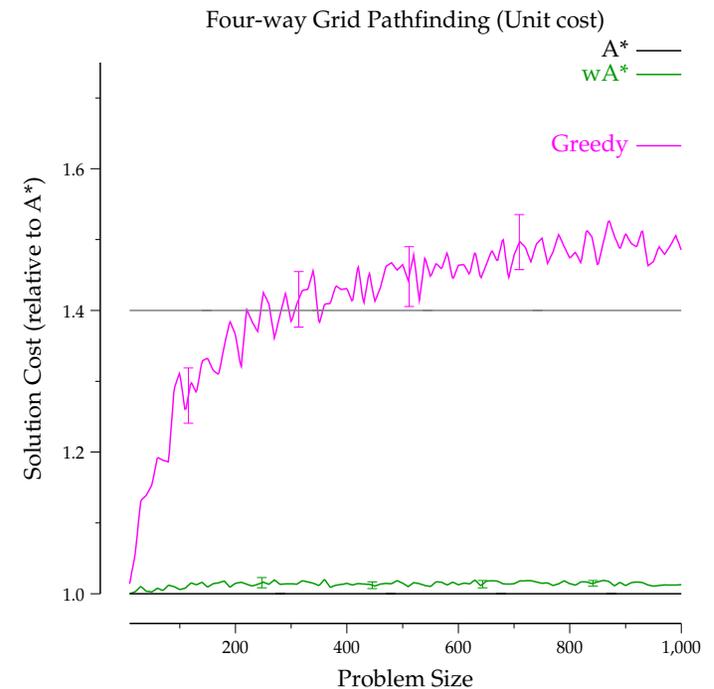
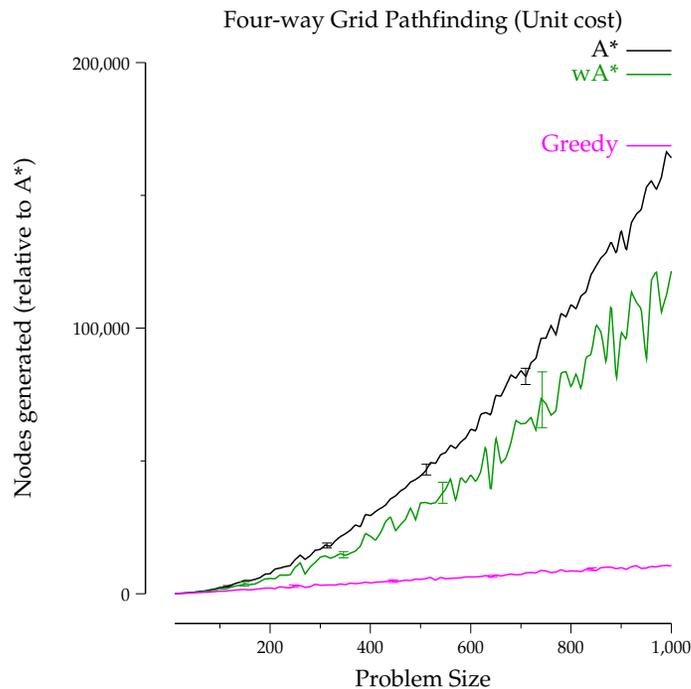
Weighted  $A^*$

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Conclusion

- Finding optimal solutions is prohibitively expensive.
- Its nice to limit suboptimality.
- Weighted  $A^*$  is a popular method for doing that.



# Motivation

Introduction

■ Motivation

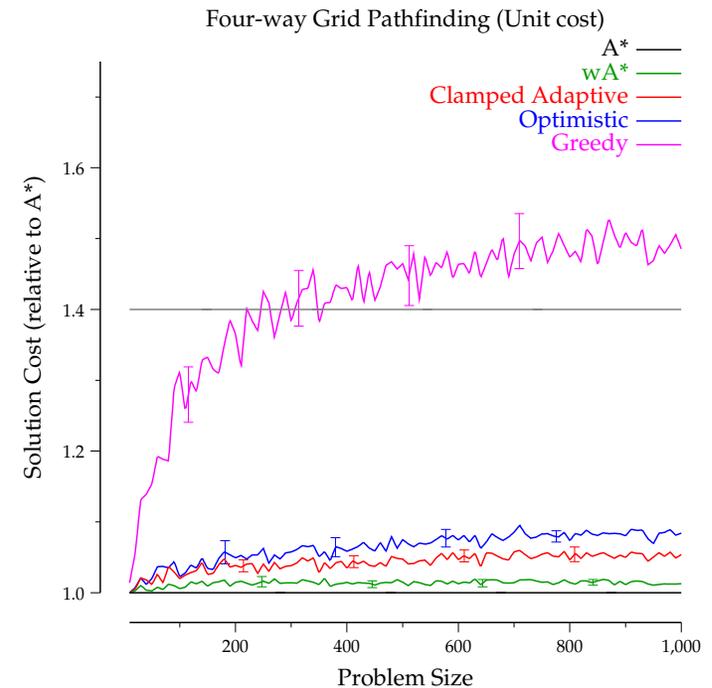
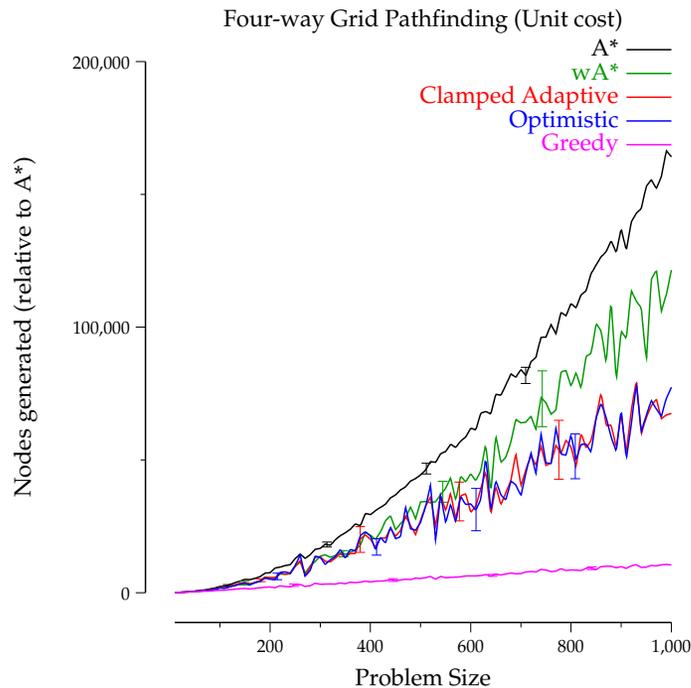
Weighted  $A^*$

Clamped Adaptive

Optimistic Search

Conclusion

- Finding optimal solutions is prohibitively expensive.
- Its nice to limit suboptimality.
- Weighted  $A^*$  is a popular method for doing that.
- This talk: two algorithms which are often better.



# Talk Outline

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Introduction

**Weighted  $A^*$**

- Weighted  $A^*$
- Bounding
- Performance

Clamped Adaptive

Optimistic Search

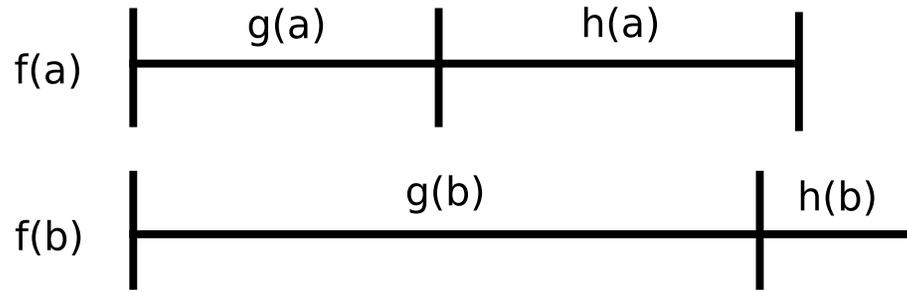
Conclusion

- **Background**  
Weighted  $A^*$
- **Strict Approach: Clamped Adaptive**  
Correct for underestimating  $h(n)$   
Bound correction to ensure  $w$ -admissibility
- **Loose Approach: Optimistic Search**  
Greedly search for a solution  
Enforce suboptimality bound afterwards

# Weighted $A^*$ (Pohl, 1970)

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$A^*$  is a best first search ordered on  $f(n) = g(n) + h(n)$



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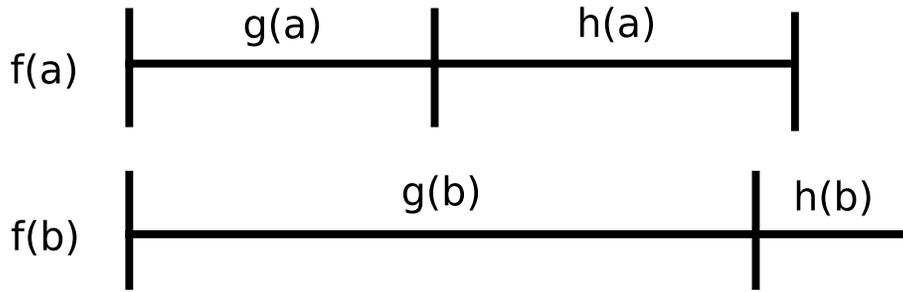
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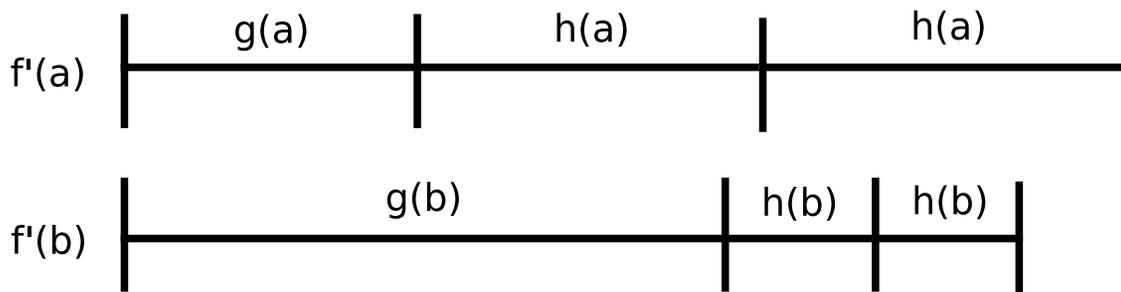
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# Weighted $A^*$ (Pohl, 1970)

$A^*$  is a best first search ordered on  $f(n) = g(n) + h(n)$



Weighted  $A^*$ :  $f'(n) = g(n) + w \cdot h(n)$



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■ Weighted  $A^*$

■ Bounding

■ Performance

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# Weighted $A^*$ (Pohl, 1970)

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■ Weighted  $A^*$

■ Bounding

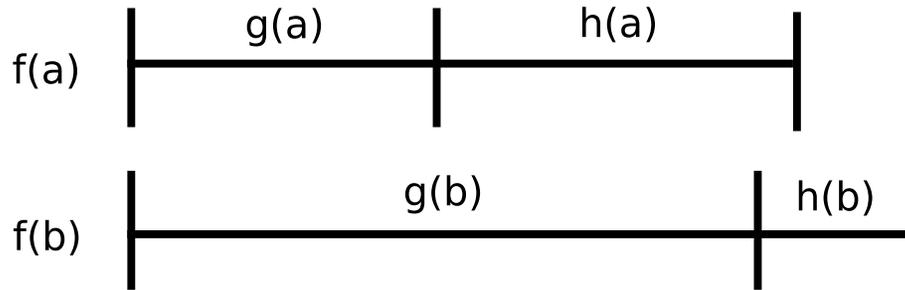
■ Performance

Clamped Adaptive

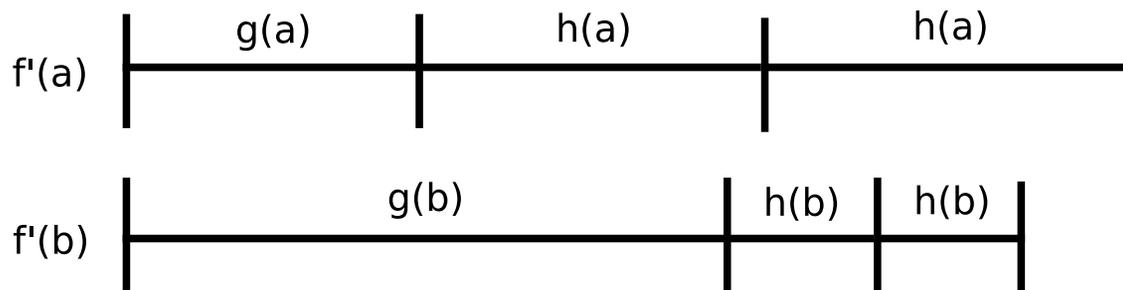
Optimistic Search

Conclusion

$A^*$  is a best first search ordered on  $f(n) = g(n) + h(n)$



Weighted  $A^*$ :  $f'(n) = g(n) + w \cdot h(n)$



What does  $w$  do?

breaks ties on  $f(n)$  in favor of high  $g(n)$

corrects for underestimating  $h(n)$

deepens search / emphasises greed

# Weighted $A^*$ Respects a Bound

Introduction

Weighted  $A^*$

■ Weighted  $A^*$

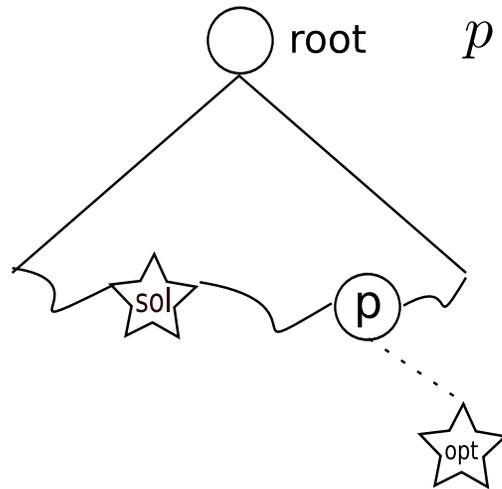
■ Bounding

■ Performance

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Conclusion



$p$  is a node in open on an optimal path to  $opt$

$$f(n) = g(n) + h(n)$$

$$f'(n) = g(n) + w \cdot h(n)$$

$$g(sol)$$

$$f'(sol) \leq f'(p)$$

$$g(p) + w \cdot h(p) \leq w \cdot (g(p) + h(p))$$

$$w \cdot f(p) \leq w \cdot f(opt)$$

$$w \cdot g(opt)$$

Therefore,  $g(sol) \leq w \cdot g(opt)$

# Weighted $A^*$ is a Popular Choice

Introduction

Weighted  $A^*$

■ Weighted  $A^*$

■ Bounding

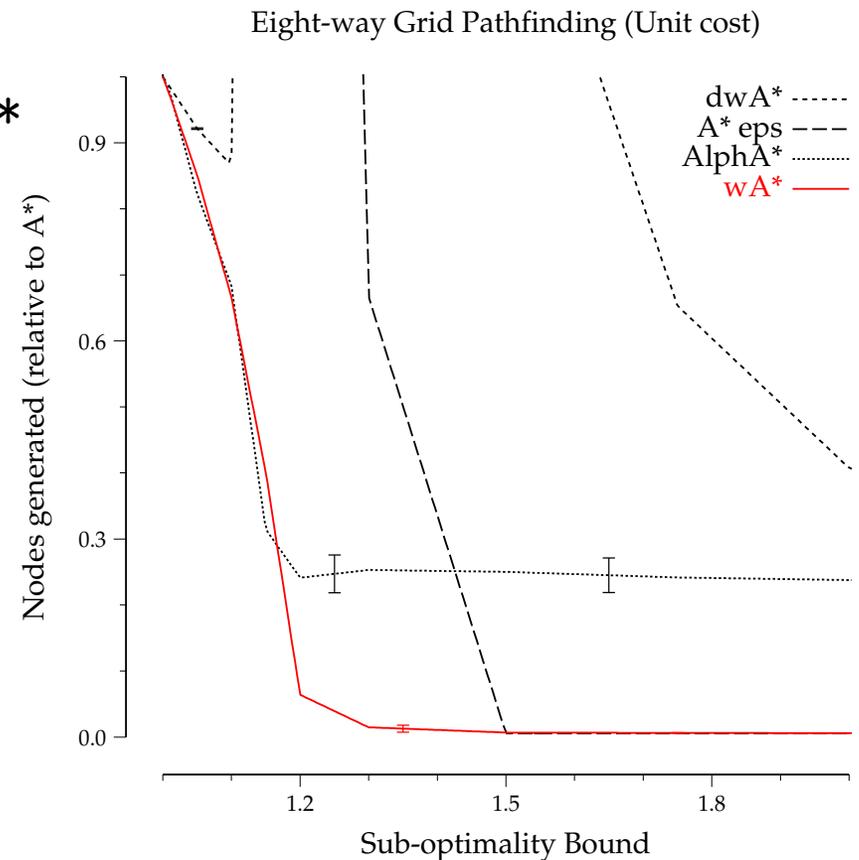
■ Performance

Clamped Adaptive

Optimistic Search

Conclusion

- Weighted  $A^*$   
Pohl (1970)
- Dynamically Weighted  $A^*$   
Pohl (1973)
- $A_\epsilon$   
Ghallab & Allard (1983)
- $A_\epsilon^*$   
Pearl (1984)
- $\text{Alpha}A^*$   
Reese & Frichs (unpublished)



# Talk Outline

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Introduction

Weighted  $A^*$

**Clamped Adaptive**

- Improving  $wA^*$
- Correcting  $h(n)$
- $w$ -Admissibility
- Performance

Optimistic Search

Conclusion

- Background  
Weighted  $A^*$
- **Strict Approach: Clamped Adaptive**  
Correct for underestimating  $h(n)$   
Bound correction to ensure  $w$ -admissibility
- Loose Approach: Optimistic Search  
Greedy search for a solution  
Enforce suboptimality bound afterwards

# Improving Weighted $A^*$

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■ **Improving  $wA^*$**

■ Correcting  $h(n)$

■  $w$ -Admissibility

■ Performance

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- If  $h$  were perfect, solutions would be found in linear time.
- How do we improve  $h(n)$ ?
  - By correcting for the error in  $h(n)$
- We'll ensure  $w$ -admissibility shortly.

# Correcting $h(n)$ with one step error

Introduction

Weighted  $A^*$

Clamped Adaptive

■ Improving  $wA^*$

■ Correcting  $h(n)$

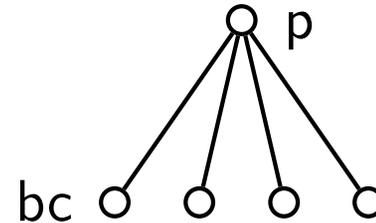
■  $w$ -Admissibility

■ Performance

Optimistic Search

Conclusion

Consider the single expansion:



Recall that  $f(n) = g(n) + h(n)$

- $f(n)$  should remain constant across parent and child.

if  $f(n) = g(n) + h^*(n)$  this would be true.  
 $g(n)$  is exact.

All the error in  $f(n)$  comes from  $h(n)$ .

- $err_h = f(bc) - f(p)$

Track a running average of  $err_h$ .

$$\hat{f}(n) = g(n) + \hat{h}(n)$$

$$\hat{h}(n) = h(n) \cdot (1 + err_h)$$

# Correcting $h(n)$ with one step error

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Weighted  $A^*$

Clamped Adaptive

■ Improving  $wA^*$

■ Correcting  $h(n)$

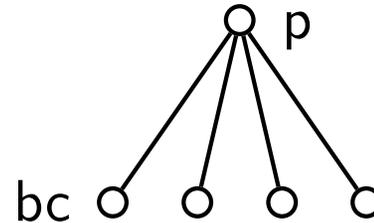
■  $w$ -Admissibility

■ Performance

Optimistic Search

Conclusion

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All the error in  $f(n)$  comes from  $h(n)$ .

- $err_h = f(bc) - f(p)$

Track a running average of  $err_h$ .

$$\hat{f}(n) = g(n) + \hat{h}(n)$$

$$\hat{h}(n) = h(n) \cdot (1 + err_h)$$

$\hat{h}(n)$  is inadmissible.

Clamping enforces  $w$ -admissibility.

# Admissibility of Clamping: Weighted A\*

Introduction

Weighted A\*

Clamped Adaptive

■ Improving  $wA^*$

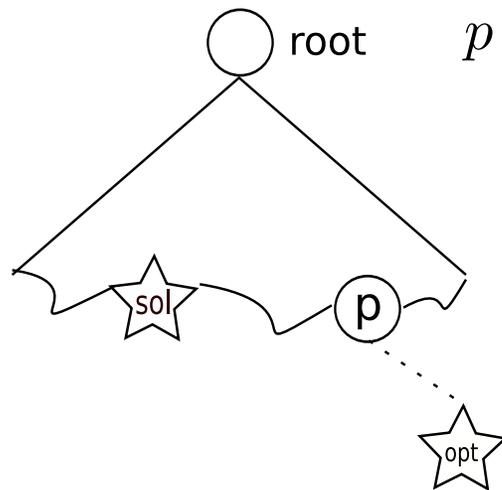
■ Correcting  $h(n)$

■  $w$ -Admissibility

■ Performance

Optimistic Search

Conclusion



$p$  is a node in open on an optimal path to  $opt$

$$f(n) = g(n) + h(n)$$

$$f'(n) = g(n) + w \cdot h(n)$$

$$g(sol)$$

$$f'(sol) \leq f'(p)$$

$$g(p) + w \cdot h(p) \leq w \cdot (g(p) + h(p))$$

$$w \cdot f(p) \leq w \cdot f(opt)$$

$$w \cdot g(opt)$$

Therefore,  $g(sol) \leq w \cdot g(opt)$

# Admissibility of Clamping: Clamped Adaptive

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Weighted  $A^*$

Clamped Adaptive

■ Improving  $wA^*$

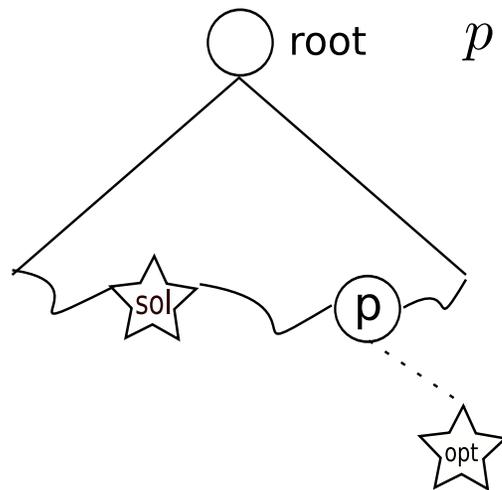
■ Correcting  $h(n)$

■  $w$ -Admissibility

■ Performance

Optimistic Search

Conclusion



$p$  is a node in open on an optimal path to  $opt$

$$f(n) = g(n) + h(n)$$

$$\tilde{f}(n) = \min(\hat{f}(n), w \cdot f(n))$$

$$g(sol) = \tilde{f}(sol)$$

$$\tilde{f}(sol) \leq \tilde{f}(p)$$

$$\tilde{f}(p) \leq w \cdot f(p)$$

$$w \cdot f(p) \leq w \cdot f(opt)$$

And  $g(s) \leq w \cdot g(opt)$  is still true.

# Empirical Evaluation

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■ Improving  $wA^*$

■ Correcting  $h(n)$

■  $w$ -Admissibility

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- Grid world path finding
    - Four-way and Eight-way Movement
    - Unit and Life Cost Models
    - 25%, 30%, 35%, 40%, 45% obstacles
  - Temporal Planning
    - Blocksworld, Logistics, Rover, Satellite, Zenotravel
- See the paper for details.

# Performance of Clamped Adaptive

Introduction

Weighted  $A^*$

Clamped Adaptive

■ Improving  $wA^*$

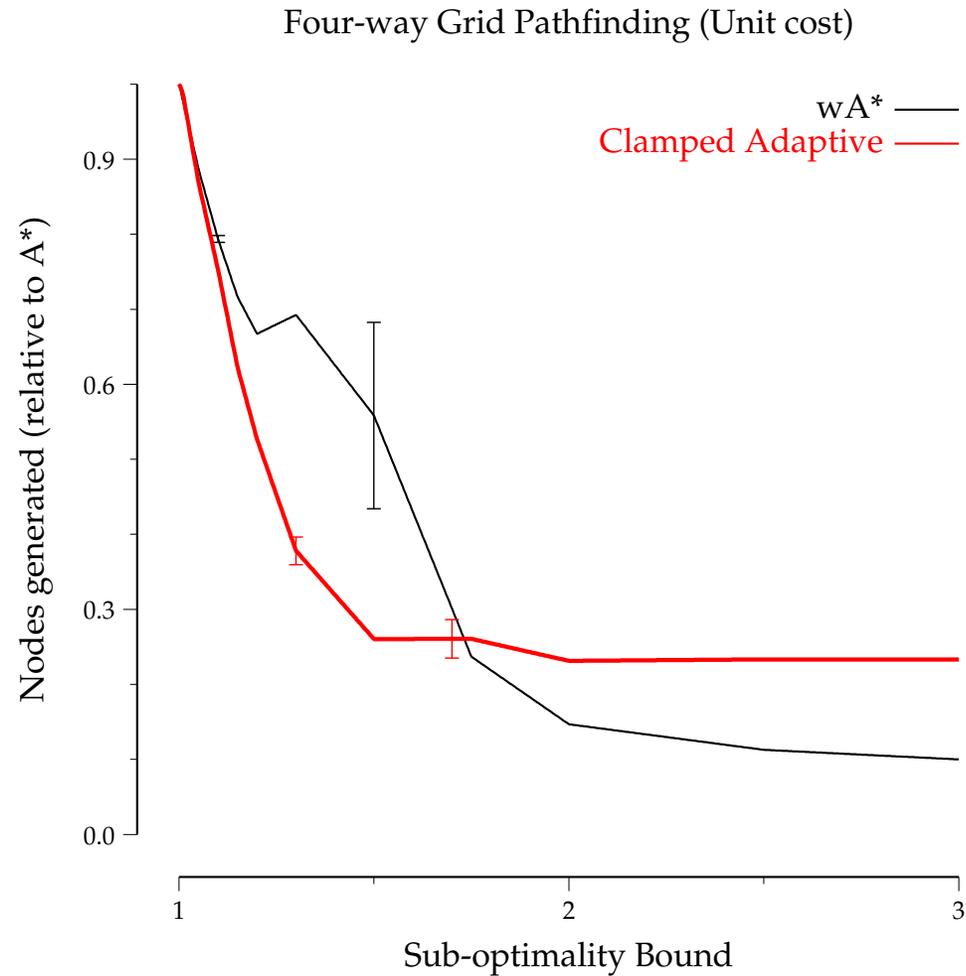
■ Correcting  $h(n)$

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# Performance of Clamped Adaptive

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Weighted  $A^*$

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■ Improving  $wA^*$

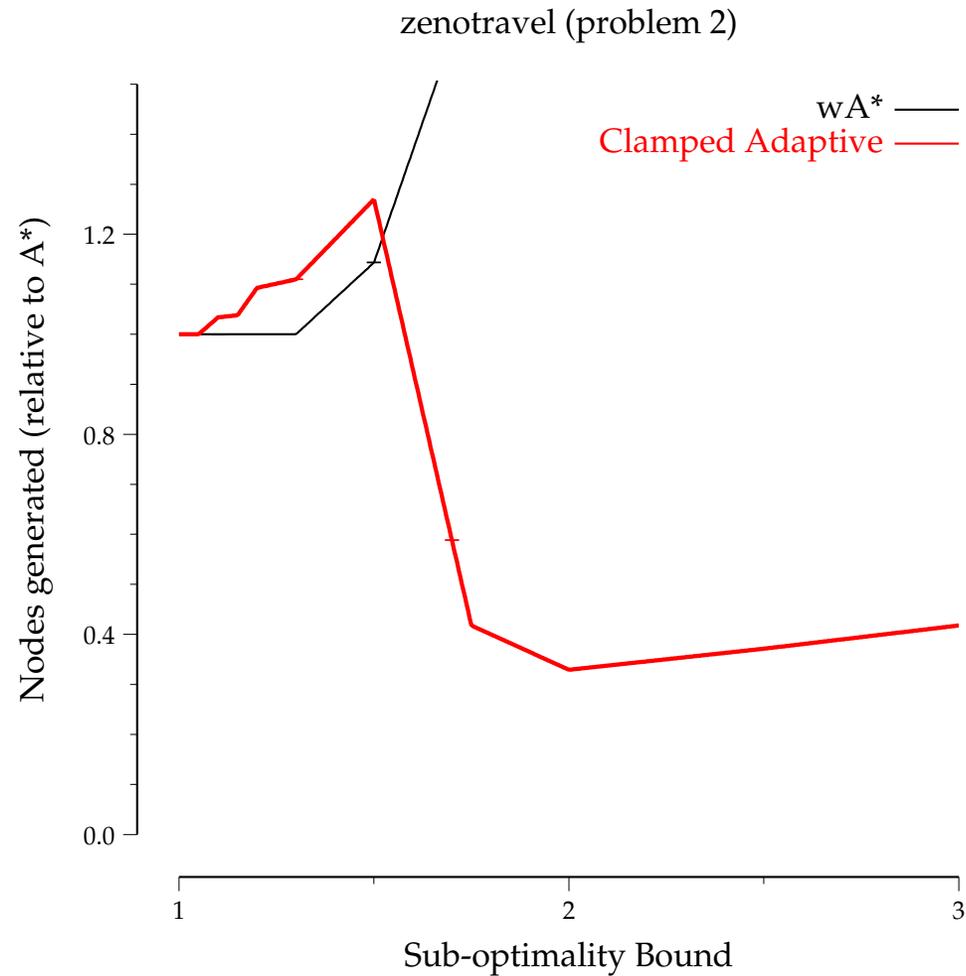
■ Correcting  $h(n)$

■  $w$ -Admissibility

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# Performance of Clamped Adaptive

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■ Improving  $wA^*$

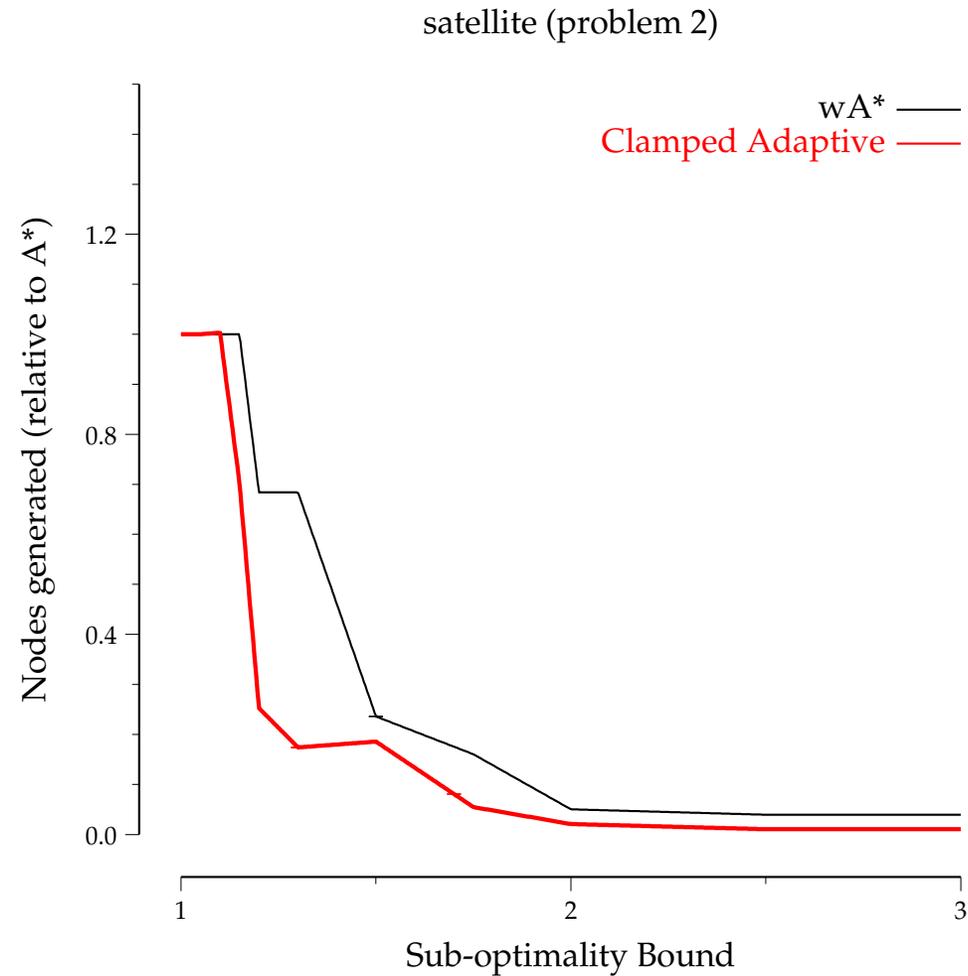
■ Correcting  $h(n)$

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# Performance of Clamped Adaptive

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■ Improving  $wA^*$

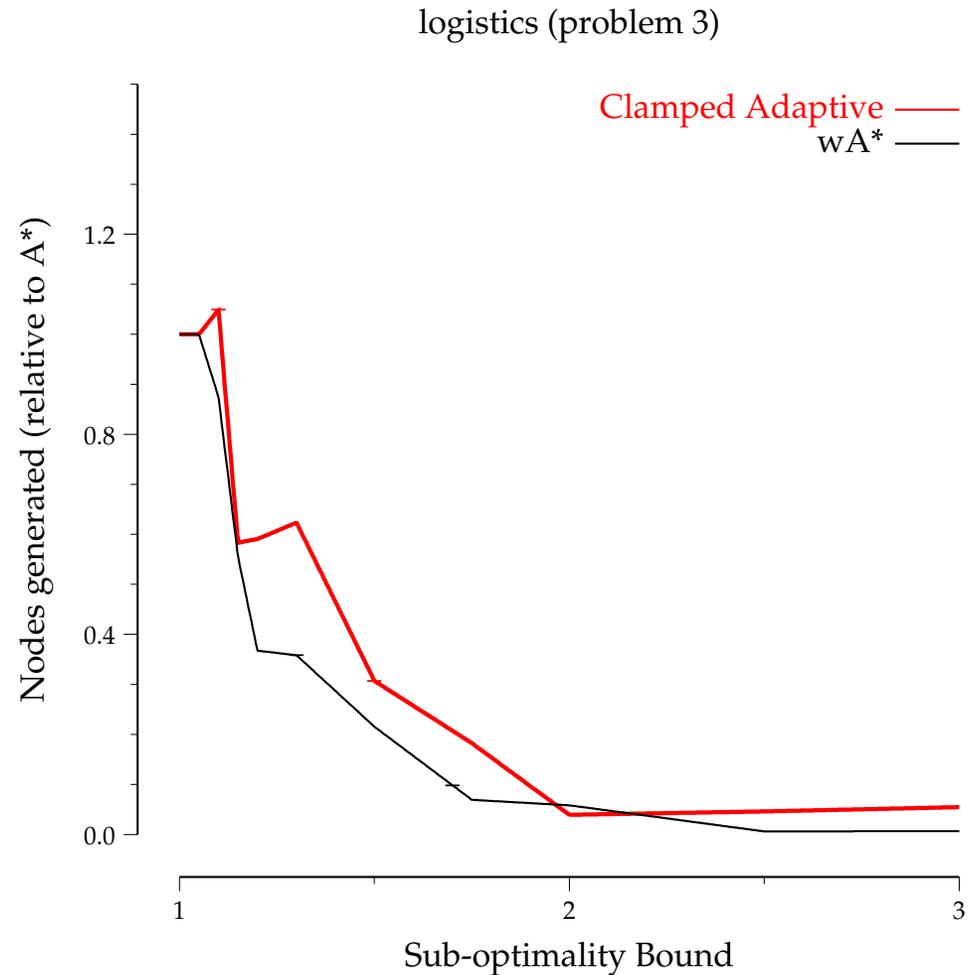
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# Clamped Adaptive: Summary

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■ Improving  $wA^*$

■ Correcting  $h(n)$

■  $w$ -Admissibility

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## Clamped Adaptive:

- On-line heuristic correction seems promising
  - Performance varies
    - Does well for small bounds
    - Fails to become greedy
- No parameter tuning needed
- Clamping for admissibility of inadmissible heuristics

# Talk Outline

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Introduction

Weighted  $A^*$

Clamped Adaptive

**Optimistic Search**

- Loose Bounds
- Solution Quality
- $w$ -Admissibility
- Performance

Conclusion

- Background  
Weighted  $A^*$
- Strict Approach: Clamped Adaptive  
Correct for underestimating  $h(n)$   
Bound correction to ensure  $w$ -admissibility
- **Loose Approach: Optimistic Search**  
Greedy search for a solution  
Enforce suboptimality bound afterwards

# Weighted $A^*$ Respects a Bound

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Optimistic Search

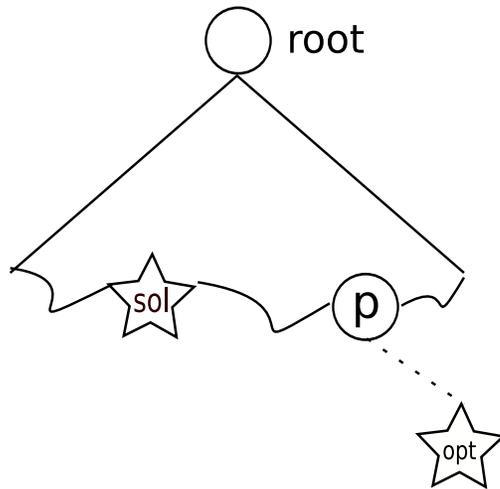
■ Loose Bounds

■ Solution Quality

■  $w$ -Admissibility

■ Performance

Conclusion



$$f(n) = g(n) + h(n)$$

$$f'(n) = g(n) + w \cdot h(n)$$

$$g(sol)$$

$$f'(sol) \leq f'(p)$$

$$g(p) + w \cdot h(p) \leq w \cdot (g(p) + h(p))$$

$$w \cdot f(p) \leq w \cdot f(opt)$$

$$w \cdot g(opt)$$

Therefore,  $g(sol) \leq w \cdot g(opt)$

# Weighted $A^*$ Respects the Bound and Then Some

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Weighted  $A^*$

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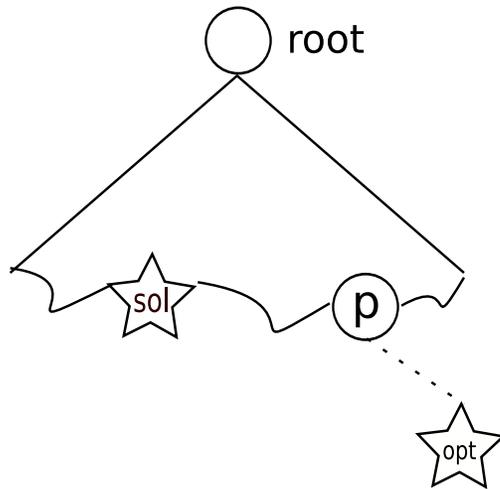
■ Loose Bounds

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■ Performance

Conclusion



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$$g(p) + w \cdot h(p) \leq w \cdot (g(p) + h(p))$$

$$w \cdot f(p)$$

$$\leq w \cdot f(opt)$$

$$w \cdot g(opt)$$

$$g(p) + w \cdot h(p) \leq w \cdot g(p) + w \cdot h(p)$$

# Solution Quality v. Bound

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■ Loose Bounds

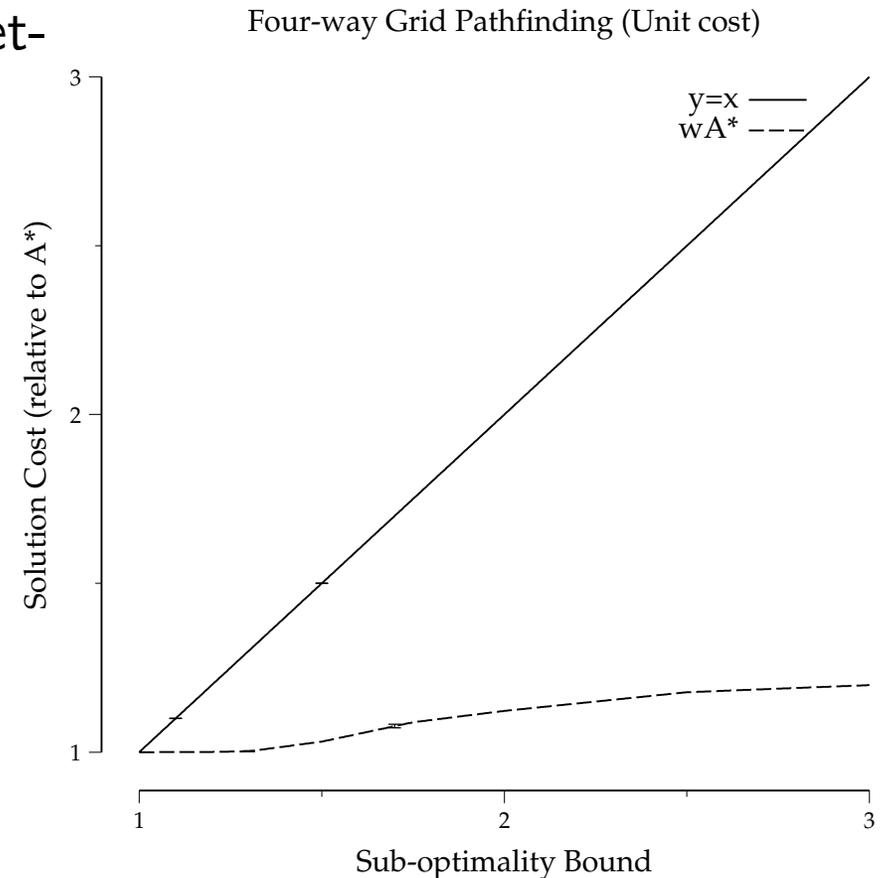
■ Solution Quality

■  $w$ -Admissibility

■ Performance

Conclusion

- $wA^*$  returns solutions better than the bound.
- Be optimistic
- Run with higher weight



How do we guarantee a suboptimality bound?

# Enforcing the Bound

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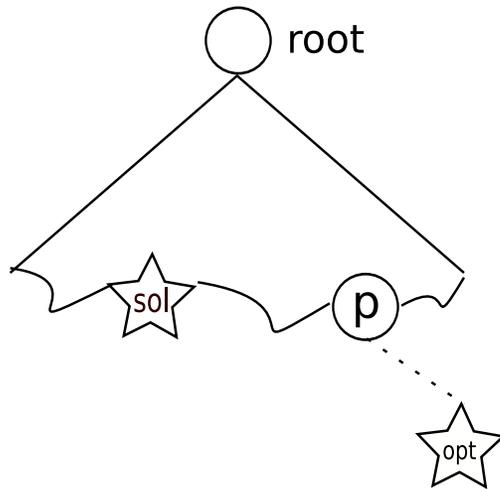
■ Loose Bounds

■ Solution Quality

■  $w$ -Admissibility

■ Performance

Conclusion



- $p$  is the deepest node on an optimal path to  $opt$

$$f(p) \leq f(opt)$$

$$f(f_{min}) \leq f(p)$$

$f_{min}$  provides a lower bound on solution cost.

Determine  $f_{min}$  by priority queue sorted on  $f$

Optimistic Search: Run a greedy search

Expand  $f_{min}$  until  $w \cdot f_{min} \geq f(sol)$

# Empirical Evaluation

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This Paper:

- Grid world path finding
  - Four-way and Eight-way Movement
  - Unit and Life Cost Models
  - 25
- Temporal Planning
  - Blocksworld, Logistics, Rover, Satellite, Zenotravel

To Appear in ICAPS:

- Traveling Salesman
  - Unit Square
  - Pearl and Kim Hard
- Sliding Tile Puzzles
  - Korf's 100 15-puzzle instances

See papers for details.

# Performance of Optimistic Search

Introduction

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■ Loose Bounds

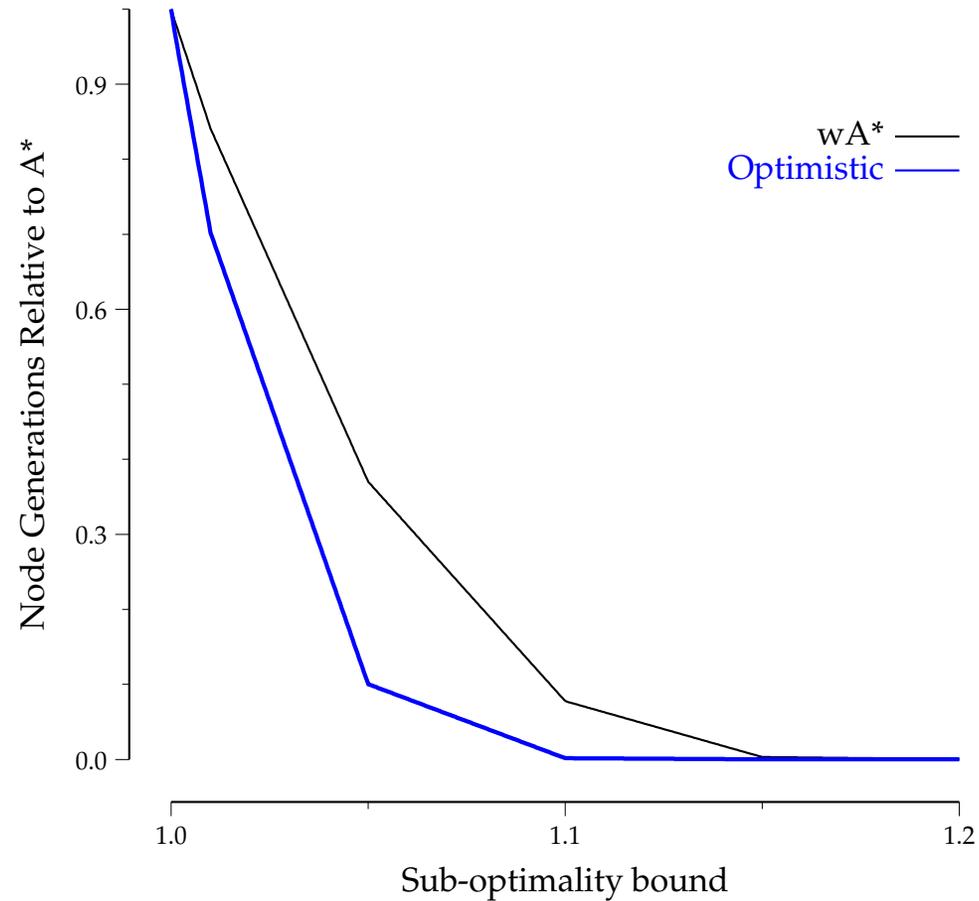
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Pearl and Kim Hard



# Performance of Optimistic Search

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■ Loose Bounds

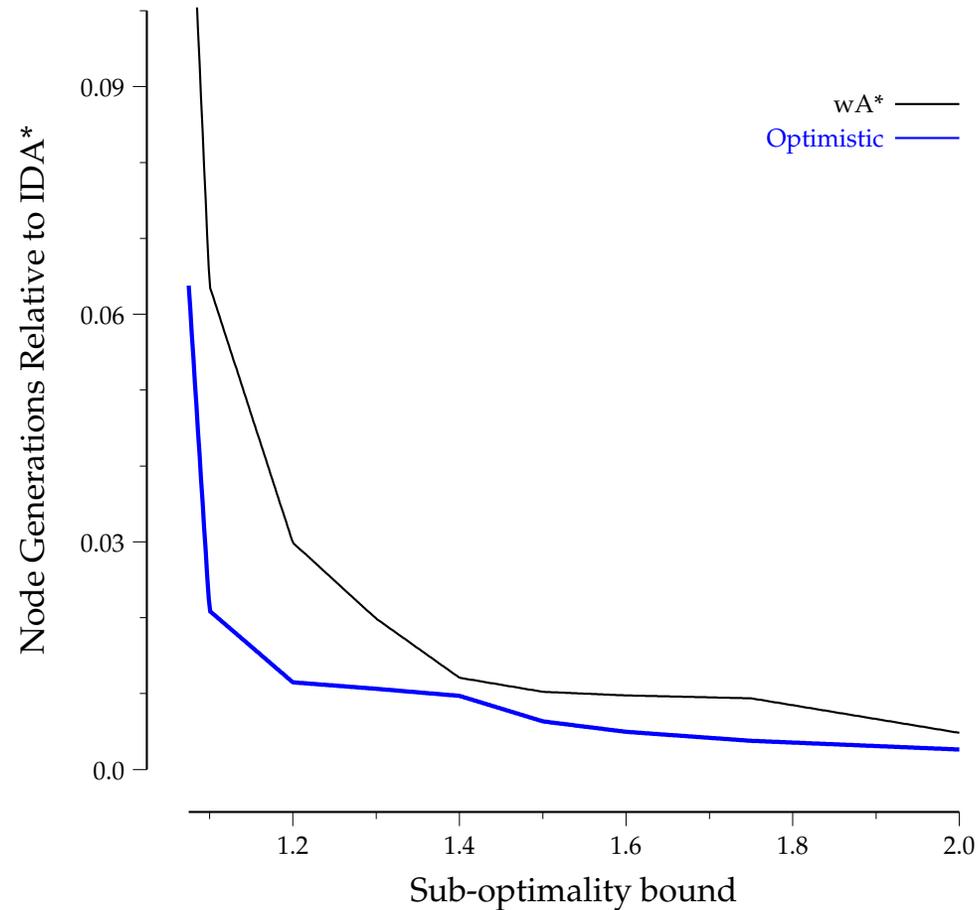
■ Solution Quality

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Korf's 15 Puzzles



# Performance of Optimistic Search

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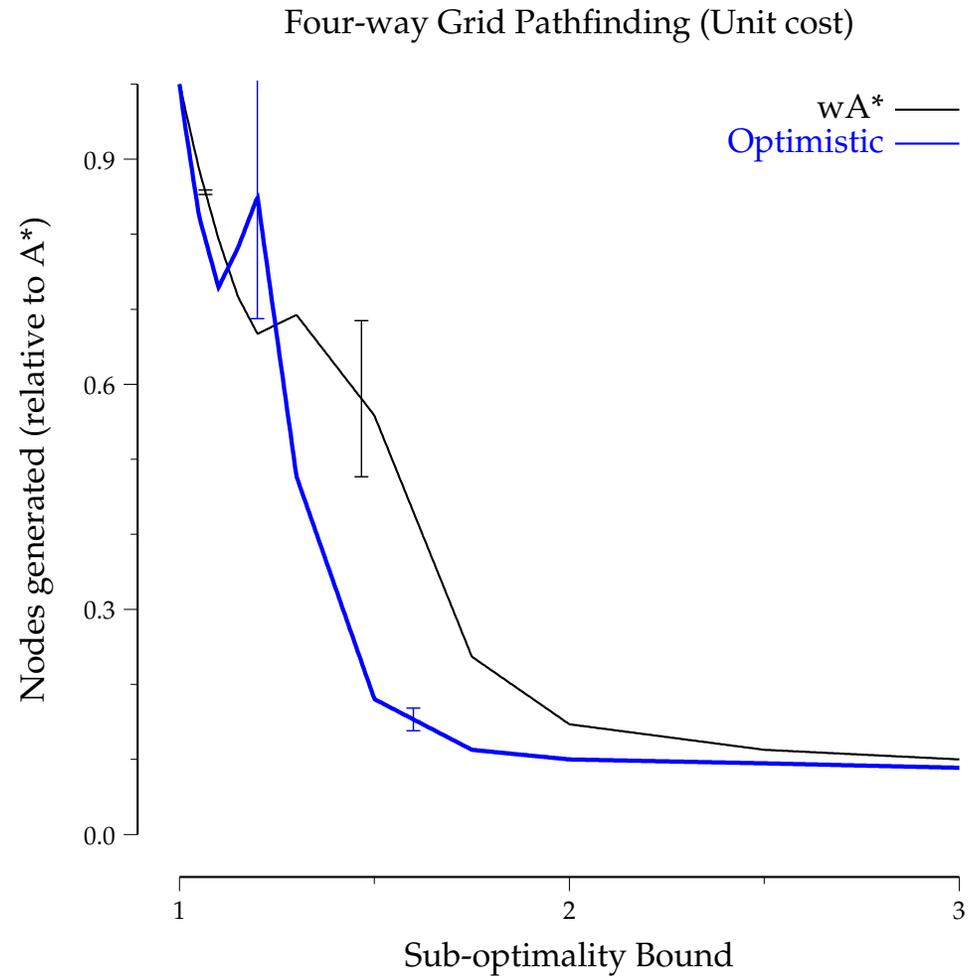
■ Loose Bounds

■ Solution Quality

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# Conclusion

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■ **Conclusion**

■ Advertising

Clamped Adaptive:

- On-line heuristic correction seems promising.
- No parameter tuning needed.

Optimistic Search:

- Performance is predictable.
- Current results are good, could be improved.

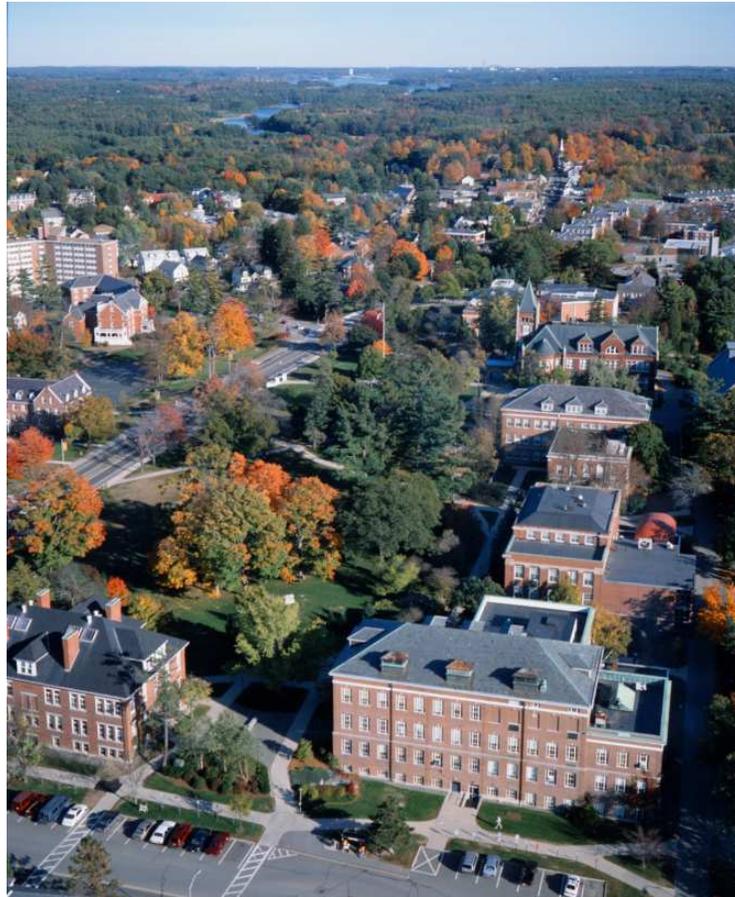
We have two algorithms that can outperform weighted  $A^*$

**We can use arbitrary heuristics for  $w$ -admissible search.**

# The University of New Hampshire

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- funding
- individual attention
- beautiful campus
- low cost of living
- easy access to Boston, White Mountains
- strong in AI, infoviz, networking, systems, bioinformatics

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■ Conclusion

■ Advertising

# Bounded Anytime Weighted A\*

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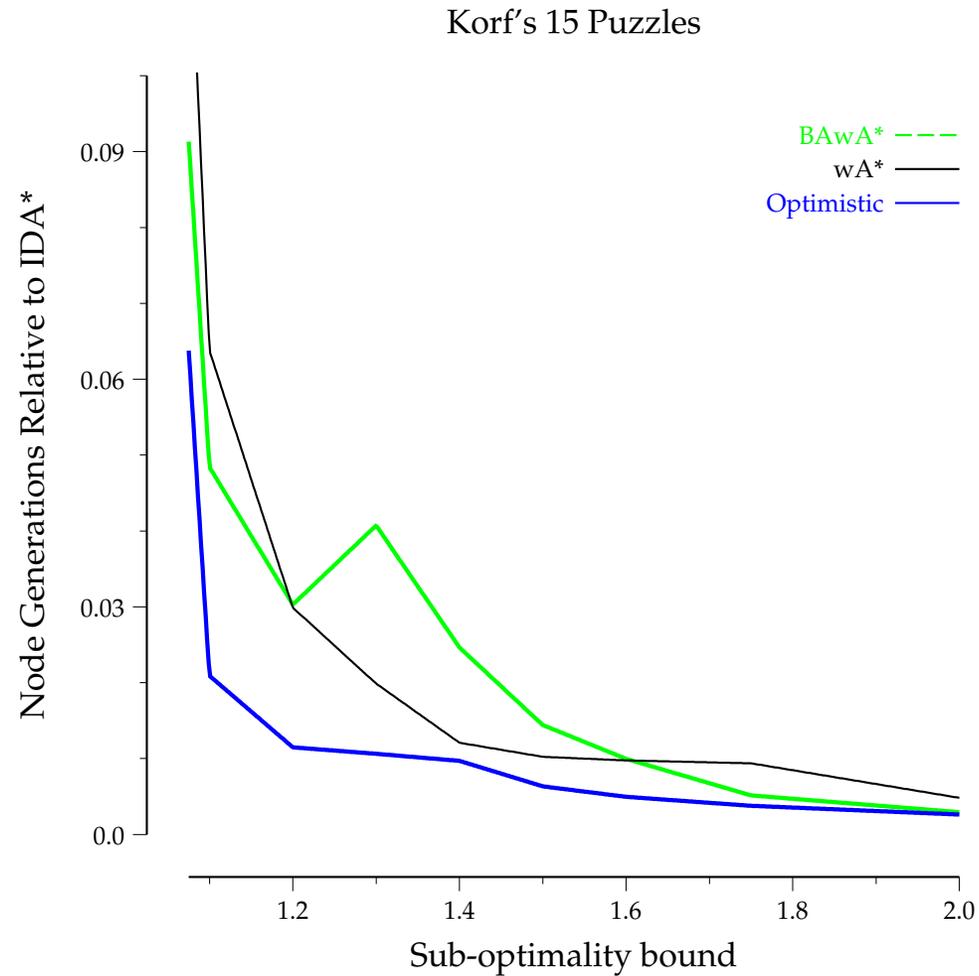
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**Bounded Anytime  
Weighted A\***



# Bounded Anytime Weighted A\*

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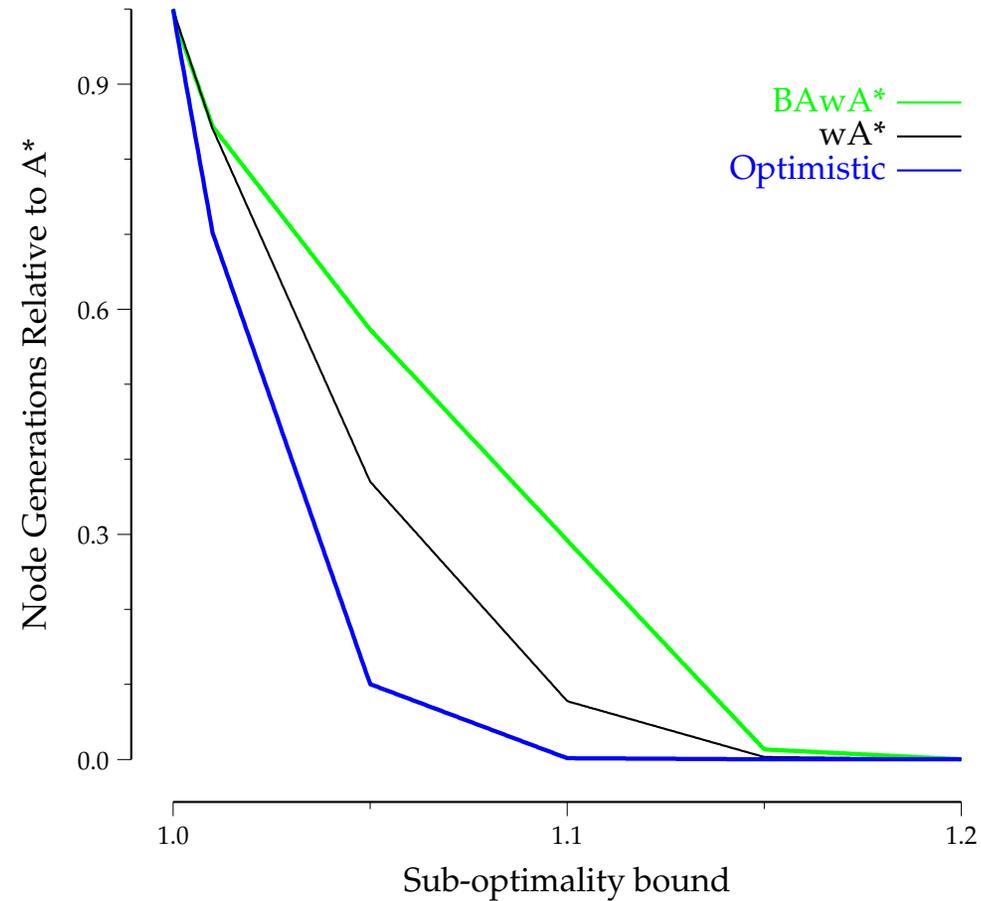
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[Bounded Anytime Weighted A\\*](#)

Pearl and Kim Hard



# Duplicate Dropping can be Important

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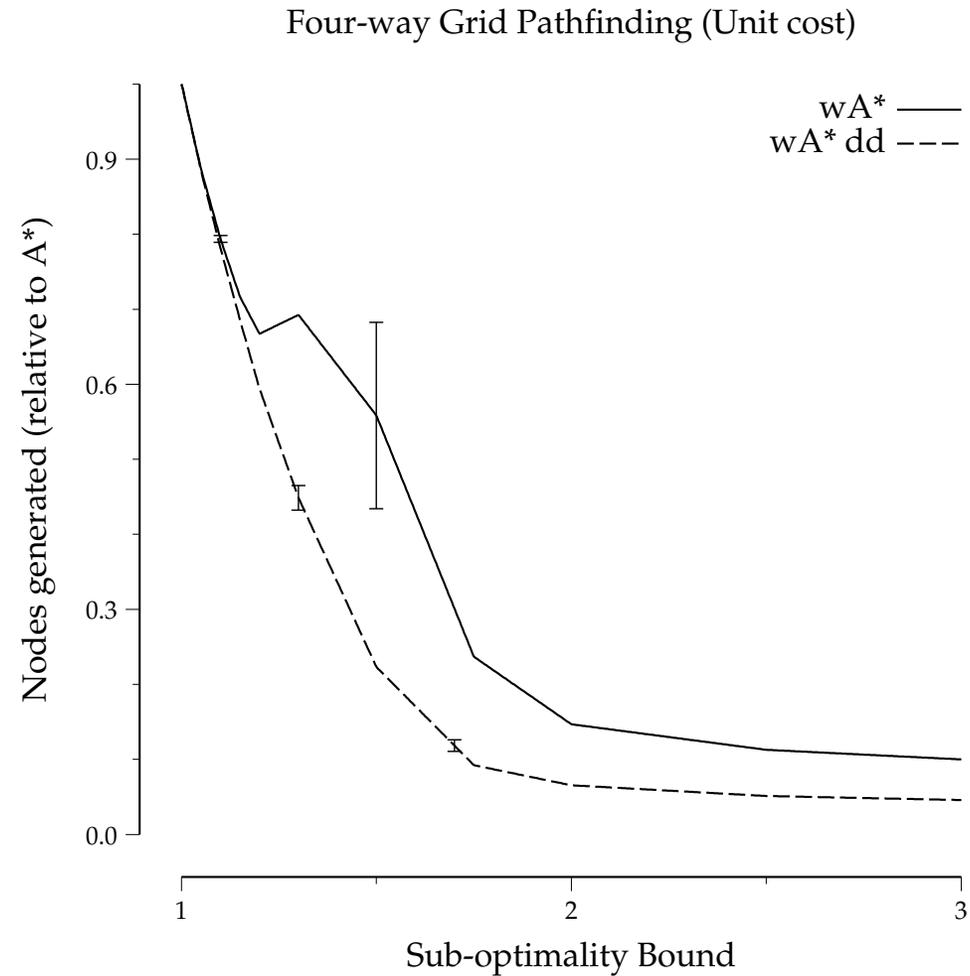
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# Sometimes it isn't

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